Energy efficient HPC software

Learning from embedded systems software development

SIAM PP12
In this presentation

• University of Bristol Micro Research Group
• Energy challenges in HPC and embedded
• Solutions from the embedded world
• Latest research
• The future of energy efficient HPC software
About us

- **Microelectronics Research Group**, University of Bristol, UK
- Multi-discipline
  - Design verification
  - Embedded systems
  - HPC
- **Energy Efficient Computing (EACO)** is part of our core research.
- Dr. Kerstin Eder’s research sponsored by the **Royal Academy of Engineering**.
About me

- MEng, Computer Systems Engineering, UoB
- PhD student in μ group
- Researching software energy modelling & optimisations
- Focus on embedded multi-core & multi-threaded systems.
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What are we trying to do?

**HPC**
- Increase:
  - Density
    - More compute power per rack
  - Performance
  - Capability
- Manage:
  - Energy
    - Electricity bill
    - Cooling infrastructure

**Embedded systems**
- Increase:
  - Density
    - Smaller components
  - Performance
  - Available features on one chip
- Manage:
  - Energy
    - Battery life
    - Cooling requirements
The key difference?

- Embedded applications have **real-time constraints**
  - Latency sensitive
  - If a deadline is missed, something **breaks**!

- HPC applications use **massive data-sets** and/or **many permutations**
  - Throughput oriented
  - Tolerate latency within acceptable limits

- The above describes general cases, not all cases!
Motivation

Lack of software support marks the low power scorecard at DAC

[...] if the software keeps cores active for no good reason [the hardware] won’t deliver a realised saving.

With limited software support, dedicated low-power circuitry could save maybe 20%.

Make the software better at controlling the power states and that difference could be three to five times.
Greater Savings at Higher Levels

According to LSI Logic & Mentor Graphics...

Why Optimize Power at the Architecture?

Power Optimization Potential

Architectural
RTL Synthesis
Gate
Layout

0% 20% 40% 60% 80% 100%

Source: LSI Logic
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Aligning SW Design Decisions with Energy Efficiency Design Goal

Key steps:

• “Choose the best algorithm for the problem at hand and make sure it fits well with the computational hardware. Failure to do this can lead to costs far exceeding the benefit of more localized power optimizations.

• Minimize memory size and expensive memory accesses through algorithm transformations, efficient mapping of data into memory, and optimal use of memory bandwidth, registers and cache.

• Optimize the performance of the application, making maximum use of available parallelism.

• Take advantage of hardware support for power management.

• Finally, select instructions, sequence them, and order operations in a way that minimizes switching in the CPU and datapath.”

Runtime -> energy?

- Can we use run-time to infer the energy consumed?
- A system’s power profile is rarely flat over the run-time.
- To know energy without directly measuring it, we need to know what is consuming time, not just how much time has passed.

Examples:
- Memory accesses
- ALU op
- SIMD
- I/O
- The many forms of “idle”
Instruction-Level Power Analysis

Energy Cost \((E)\) of a program \((P)\):

\[
E_P = \sum_i (B_i \times N_i) + \sum_{i,j} (O_{i,j} \times N_{i,j}) + \sum_k E_k
\]

- Instruction base cost, \(B_i\), of each instruction \(i\), occurring \(N_i\) times
- Circuit state overhead, \(O_{i,j}\), for each instruction pair \(i\) and \(j\).
- Other instruction effects (stalls, cache misses, etc)

ILPA: Doesn’t always work

- XMOS XS1 embedded processor
- Up to eight threads per core
- Four stage pipeline
- Simple scheduling
- At 500MHz, 125MIPS per thread for <= 4 threads
Fixing the model

- Thread interaction example
  - I/O & protocols govern activity
  - More detail gives a higher accuracy model.
  - The more we can predict, the more energy we can save.
Doing *nothing* well

- One can spend a lot of time waiting for I/O
  - Sensors
  - Networks
  - Storage devices
- What do we do when waiting?
  - Early computation
  - Outstanding tasks
  - *Go to sleep*
Take a nap

- Frequency scaling can be fast (DFS)
  - Linear reduction in power
- Voltage and frequency scaling is slow (DVFS)
  - Quadratic reduction in power
- Turning off altogether is really slow
  - Well, turning back on is.
  - Best reduction in power

Formulae for calculating and controlling power/energy

\[
\begin{align*}
P_{\text{static}} &= V_{\text{core}} \times I_{\text{leak}} \\
P_{\text{dynamic}} &= A_{\mu} \times C_{\text{sw}} \times V_{\text{core}}^2 \times F \\
E &= T \left( P_{\text{static}} + P_{\text{dynamic}} \right)
\end{align*}
\]

- We work within the tolerable latencies for the tasks and protocols we’re using.
  - If we have 1ms to respond to the next signal, we can scale back the voltage while we wait for it.
  - If we have 1920ns, we have to re-think.
Software induced insomnia

• One of our biggest problems...
• HW has to guess when it can use low power states. Why?
• Because if we let SW do it, it takes too long. WHY?
• HW & SW designers need to understand each other better!
• Knowing how the SW influences the HW’s energy saving features is key to SW energy modelling and optimisation on modern processors.
The ideal strategy

- Find a frequency & voltage at which we achieve 100% utilisation in time **and** meet all deadlines.
  - No slack
  - No extra latencies from DVFS

- This can be difficult.
  - So we’re always searching for better task allocation strategies
  - And trying to make it quicker and easier to use energy saving features
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Building a better model...

• Example: 32-bit XMOS hardware.
• The full width of the data path is always active.
  – No architectural specialisation for narrower data.
• Let’s compare the switching with 32-bit and 16-bit values.
• And let’s also look at the operand count for instructions.
- The “hottest” instructions tend to have more operands.
- 16-bit: 10-25% improvement for some instruction pairings.
What does this tell us?

• A **cooperative** hardware/software optimisation.
• Possible base for a simple model.
• Needs expanding to deal with communication and other I/O.
  – Will give us the ability to model the energy trade-off between communication and computation.
• The challenge then becomes **communicating this data to the software engineer**.
  – Enable experimentation, *without* expensive re-runs.
  – Produce an algorithm that’s a **good hardware fit**.
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Modelling the HPC software

• Through static analysis of program code, determine our resource usage:
  – What components are we exercising?
  – FPU/SIMD/GPU/Disk/Comms
• Where is the energy going?
• What resources are we **not** using?
  – What can we **slow down**/put to sleep?
Profiling

- Run-time profiling is often used to guide performance optimisations.
- A workload that is predictable can help us with more than just performance.
- Profile resource usage and set our frequencies, voltages, link states and task allocations accordingly.
Utilising multi-core/multi-threaded

- Assign less demanding tasks to low frequency cores.
- Move tasks that interfere with other optimisation efforts onto a different core.
- Example: ARM’s big.LITTLE SoC design strategy.
- We have to deal with the timing & communication implications of doing this.
Finding the limit

- For **existing hardware**...
- Analyse energy efficiency in commonly used applications & libraries.

- **A call to arms:**
  - Looking for examples that we can hand-optimize
  - Measure the gap between manual opt. & tools.

- We also want to know **how you value your tools**
  - What do they tell you about resource usage?
A new paradigm

- Energy as a 1st class design goal...

- Allocate compute resources in units of energy, not just time.
- Captures both execution duration and power efficiency.
- Forces HPC application developers to think about energy.
- Energy-aware tools become *necessary* for developing new, energy efficient HPC code.

`in 15ms do {...}`
`in 29000mJ do {...}`
Thank you!

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